# Algorithm

LAST MINUTE NOTES

## Algorithm – Input, Output, Definiteness, Finiteness, Effectiveness

1) Worst Case Analysis (Usually Done) - calculate upper bound on running time of an algorithm (a situation where algorithm takes maximum time)

 $f(n) \leq c \cdot g(n)$ 

2) Average Case Analysis (Sometimes done) - we take all possible inputs and calculate computing time for all of the inputs.

3) Best Case Analysis - calculate lower bound on running time of an algorithm.

Best Case – Minimum time required for program execution. Average Case – Average time required for program execution. Worst Case – Maximum time required for program execution. ILI -> 011 Assume Building V

8+3

## Asymptotic Notation

Theorem

 $- \mathbf{p}_{\mathbf{c}}$ 

() (n)

<u>S2(n)</u>

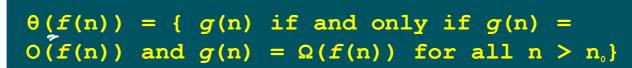
 $\boldsymbol{\times}$ 

 $f(n) \leq c.q(n)$ 

 $g(n) \leq c.f(n)$ 

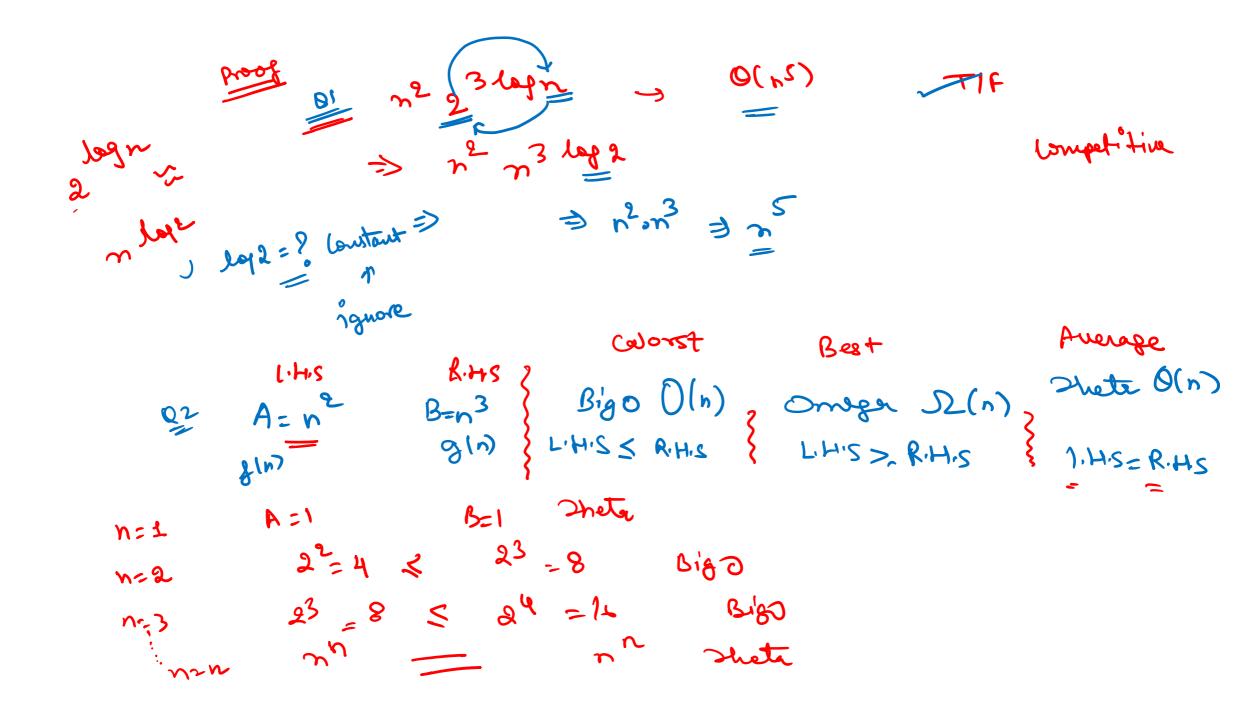
•O Notation - The notation O(n) is the formal way to worst express the upper bound of an algorithm's running time. It can measures the worst case time complexity or the longest amount of time an algorithm can possibly take to complete. •O Notation - The notation  $\Omega(n)$  is the formal way to express the lower bound of an algorithm's running time. It

express the lower bound of an algorithm's running time. It measures the best case time complexity or the best amount of time an algorithm can possibly take to complete. • $\theta$  Notation - The notation  $\theta(n)$  is the formal way to express both the lower bound and the upper bound of an algorithm's running time.





| constant                      | O(1)               | ~ les                   |
|-------------------------------|--------------------|-------------------------|
| logarithmic                   | O(log n)           |                         |
| linear                        | O(n)               | - power 2               |
| n log n                       | O(n log n)         |                         |
| <ul> <li>quadratic</li> </ul> | O(n <sup>2</sup> ) | power 2<br>power 3<br>n |
| cubic                         | O(n <sup>3</sup> ) | power 3                 |
| polynomial                    | n <sup>O(1)</sup>  | n                       |
| exponential                   | 2 <sup>O(n)</sup>  | 2 <sup>n</sup>          |

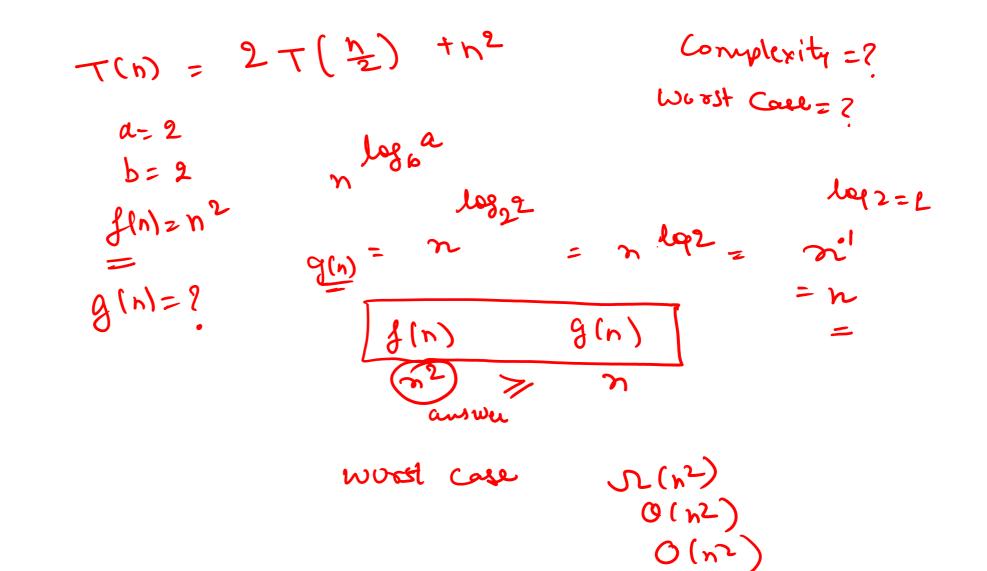


 $\begin{array}{rcl} \text{main(1)} & 500 \text{ lallel} | \text{ (nore} \\ & & & & \\ & & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\$ execute finite -> O(1) (infinite -> O(1)) (infinite -> O(1) (infinite -> O(1)) (infini 3 3 <u>(</u><u>s</u>\_ 0,1 lig 2 = 1 DS vast concept , Content -> log 4 = log 2 = 2 log 2 = 2+1=2 log 16 = 21 = log 2<sup>4</sup> = 4 log 2 = 4x1 = 4 a  $leg_n b = b leg_n a$   $leg_n a^n = n leg_n a$ 

Complexity ? Master alos. 01 ) f(n) recurrence Binary eare Sufeniers Segrih ラ a= 8 0(n) f(n) = g(n)-sorted b= 2  $\leq g(n)Q(n)$ - DAC  $f(n)=n^2$ 7, g(h) 1(h) - + 61 (gn) a,b,g(n)3 لمع 2 > log 8 n-elen. f(n)= n2 Olign)  $g(n) = n^3$ T(n) = Worst g(n) Accurrence Relation 

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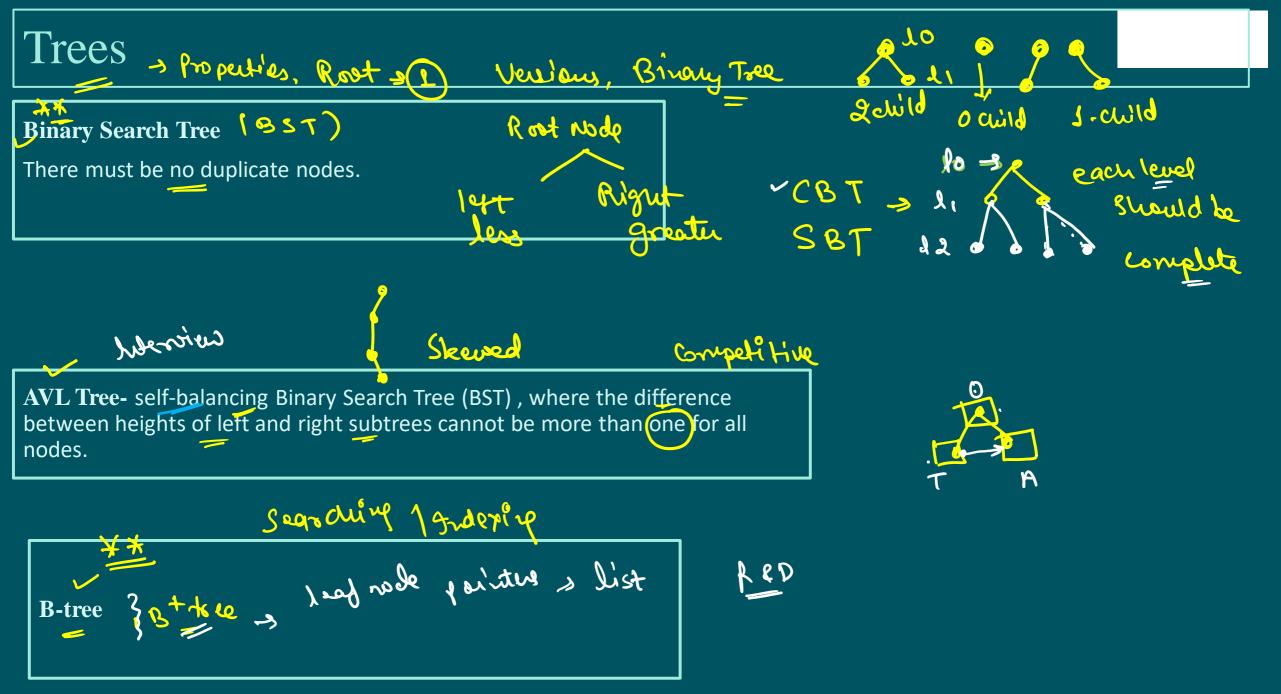
9 
$$T(n) = 16T \left(\frac{n}{4t}\right) + n$$
  
 $a T \left(\frac{h}{4t}\right) + n$   
 $a T \left(\frac{h}{4t}\right) + \delta(n)$   
 $b = 4 - 7/2$   
 $b(n) = n$   
 $b = 2 - 160$   
 $b = 160$   

$$\frac{1}{2} + n$$

$$\frac{1}{2} + n$$

$$\frac{1}{2} + 1$$

(a) T(n) = 3T(-1)(02) T(n) = 2T 837 +1n) = 1; 04) T(n) = (1) T (10) = (9.6) T(n) =Remark =







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#### Jean ~ array linned list Algorithm **Adjacency Matrix** Adjacency List DFS O(V \* V) O(V+E) O(V \* V) BFS O(V+E) O(V^2) O(E log V) Dijkstra Prim's Kruskal's



| Algorithm | Worst <u>Case</u>  | <u>Average</u><br><u>Case</u> | Best Case          |           | Algorithm           | Worst <u>Case</u>        | <u>Average</u><br><u>Case</u> | Best Case     |       |           |
|-----------|--------------------|-------------------------------|--------------------|-----------|---------------------|--------------------------|-------------------------------|---------------|-------|-----------|
| Selection | Θ(n²)              | Θ(n²)                         | Θ(n²)              |           | Topological sorting | O(V+E)                   |                               |               |       |           |
| Bubble    | Θ(n²)              | Θ(n²)                         | Θ(n <sup>2</sup> ) | <b>n)</b> |                     | Θ(n²)                    | Θ(n²)                         | Θ(n²)         |       |           |
| Insertion | Θ(n²)              | Θ(n²)                         | Θ(n)               |           | с.<br>С             | Θ(n²)                    | Θ(n²)                         | Θ(n)          |       |           |
| Quick     | Θ(n <sup>2</sup> ) | Θ(nlgn)                       | Θ(nlgn)            |           |                     | Θ(n²)                    | Θ(nlgn)                       | Θ(nlgn)       |       |           |
| Merge     | Θ(nlgn)            | O(nlgn)                       | Θ(nlgn)            |           |                     | Θ(nlgn)                  | Θ(nlgn)                       | Θ(nlgn)       |       |           |
| Неар      | Θ(nlgn)            | Θ(nlgn)                       | Θ(nlgn             |           | 0                   |                          | Θ(nlgn)                       | Θ(nlgn)       | n/a   |           |
|           |                    | 0(m) 5<br>6(1)                | 2 0( Leg           | (n)       |                     | Algorithm                | Worst<br>Case                 | Avera<br>Case |       | Best Case |
|           | v=1<br>v=1         | 0(2)                          |                    | 9(2)      |                     | <u>_inear</u><br>Search  | (n)                           | Θ(n)          | array | Θ(1)      |
| v         | - S                | 0(3                           |                    | vers      |                     | <u> Binary</u><br>Search | Q (logn)                      |               | IY    | O (1)     |



type.

**2.***Conquer:* Recursively solve these subproblems **3.***Combine:* Appropriately combine the answers

2) Quicksort is a sorting algorithm. The algorithm picks a pivot **1.Divide:** Break the given problem into subproblems of same element, rearranges the array elements in such a way that all elements smaller than the picked pivot element move to left side of pivot, and all greater elements move to right side. Finally, the algorithm recursively sorts the subarrays on left and right of pivot element.

|                       | <u>∽ X</u>          | · · · · · · · · · · · · · · · · · · · |   |
|-----------------------|---------------------|---------------------------------------|---|
| Divide & Conquer      | Recurrence Relation | Time Complexity                       |   |
| Binary Search         |                     | O( <mark>p</mark> Logn)               |   |
| Quick Sort            |                     | O(nLogn)                              | 7 |
| Merge Sort            |                     | O(nLogn)                              |   |
| Closet pair of points |                     | O(nLogn)                              |   |

1) Binary Search is a searching algorithm. In each step, the algorithm compares the input element x with the value of the middle element in array. If the values match, return the index of middle. Otherwise, if x is less than the middle element, then the algorithm recurs for left side of middle element, else recurs for right side of middle element

3) Merge Sort is also a sorting algorithm. The algorithm divides the array in two halves, recursively sorts them and finally merges the two sorted halves.

4) <u>Closest Pair of Points</u> The problem is to find the closest pair of points in a set of points in x-y plane. The problem can be solved in  $O(n^2)$  time by calculating distances of every pair of points and comparing the distances to find the minimum.

Greedy is an algorithmic paradigm that builds up a solution piece by piece, always choosing the next piece that offers the most obvious and immediate benefit. Greedy algorithms are used for optimization problems. An optimization problem can be solved using Greedy if the problem has the following property: At every step, we can make a choice that looks best at **2)** Prim's Minimum Spanning Tree: In Prim's algorithm also, we problem.

3) Dijkstra's Shortest Path: The Dijkstra's algorithm is very similar to Prim's algorithm. The shortest path tree is built up, edge by edge. We maintain two sets: set of the vertices already included in the tree and the set of the vertices not yet included. The Greedy Choice is to pick the edge that connects the two sets and is on the smallest weight path from source to the set that contains not yet included vertices.

#### 1) Kruskal's Minimum Spanning Tree (MST): In Kruskal's

algorithm, we create a MST by picking edges one by one. The Greedy Choice is to pick the smallest weight edge that doesn't cause a cycle in the MST constructed so far.

create a MST by picking edges one by one. We maintain two sets: set of the vertices already included in MST and the set of the vertices not yet included. The Greedy Choice is to pick the smallest weight edge that connects the two sets.

4) Huffman Coding: Huffman Coding is a loss-less compression technique. It assigns variable length bit codes to different characters. The Greedy Choice is to assign least bit length code to the most frequent character.

| Greedy Approach | Recurrence Relation | Time Complexity |   |
|-----------------|---------------------|-----------------|---|
| Kruskal's       |                     | O(nLogn)        | ٦ |
| Prim's          |                     | O(nLogn)        |   |
| Dijkstra        |                     | O(nLogn)        |   |
| Huffman Coding  |                     | O(nLogn)        |   |

## Greedy algorithm

### Application

Travelling Salesman Problem
Prim's Minimal Spanning Tree Algorithm
Kruskal's Minimal Spanning Tree Algorithm
Dijkstra's Minimal Spanning Tree Algorithm
Graph - Map Colouring
Graph - Vertex Cover
Knapsack Problem
Job Scheduling Problem

·DP ( Dynamic Pre)

Fibonacci number series

- Knapsack problem
- Fower of Hanoi
- •All pair shortest path by Floyd-Warshall
- •Shortest path by Dijkstra
- Project scheduling

·DAC ( d'vide elonquer)

Merge Sort
Quick Sort
Binary Search
Strassen's Matrix Multiplication
Closest pair (points)

Dynamic Programming is an algorithmic paradigm that solves a given complex problem by breaking it into subproblems and stores the results of subproblems to avoid computing the same results again

**1.Overlapping Subproblems:** Dynamic Programming is mainly used when solutions of same subproblems are needed again and again. In dynamic programming, computed solutions to subproblems are stored in a table so that these don't have to be recomputed.

**2.Optimal Substructure**: A given problems has Optimal Substructure Property if optimal solution of the given problem can be obtained by using optimal solutions of its subproblems.

| Dynamic Programming           | Recurrence Relation | Time Complexity |
|-------------------------------|---------------------|-----------------|
| Floyd warshall                |                     | O(nLogn)        |
| Bellman Ford                  |                     | O(nLogn)        |
| Longest Common<br>Subsequence |                     | O(nLogn)        |
|                               |                     | O(nLogn)        |

## BackTracking

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Backtracking is an algorithmic paradigm that tries different solutions until finds a solution that "works". Backtracking works in an incremental way to attack problems. Typically, we start from an empty solution vector and one by one add items .Meaning of item varies from problem to problem. Example: <u>Hamiltonian Cycle</u>

### Search

Interpolation search is an improved variant of binary search. algorithm works on the probing position of the required value. For this algorithm to work properly, the data collection should be in a sorted form and equally distributed. **O(log (log n))** 

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